# **Estimation**

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## Point estimation as a decision problem

• General decision problem: choose  $\delta(Y)$  to minimize

 $E[\mathcal{L}(\theta, \delta(Y)) | Y]$ .

• Estimation: We want to observe Y, then set  $\delta$  as close as possible to  $\theta.$  I.e.,

$$\mathcal{L}(\theta, \delta) = \mathcal{M}(\rho(\theta, \delta)),$$

where  $\rho$  is a metric (a measure of distance between points) and M is an increasing function.

- Examples of  $\rho$ : Ordinary Euclidean distance  $\sqrt{\sum(a_i^2)}$ , uniform  $\max(|a_i|)$ , absolute deviation  $\sum(|a_i|)$ .
- There are different versions of estimation, depending on the form of  $\mathcal{M}(\rho(\cdot)).$

#### **Estimation with quadratic loss**

- $\mathcal{M}(\rho(a)) = a'Wa$ , where W p.s.d.
- Regardless of what W is, optimal  $\delta$  is  $\delta(Y) = \hat{\theta}(Y) = E[\theta \mid Y]$ .
- Proof: Suppose  $\delta(Y) = \hat{\delta}(Y) + \gamma(Y)$ , with  $\gamma(Y)$  not zero. Then

$$\begin{split} E[\mathcal{L}(\theta, \delta(Y)) \mid Y] \\ &= E\left[(\theta - \hat{\theta}(Y))'W(\theta - \hat{\theta}(Y)) + 2(\theta - \hat{\theta}(Y))'W\gamma(Y) + \gamma(Y)'W\gamma(Y) \mid Y\right] \\ &= E\left[(\theta - \hat{\theta}(Y))'W(\theta - \hat{\theta}(Y)) \mid Y\right] + \gamma(Y)'W\gamma(Y) \geq \mathcal{L}(\theta, \hat{\theta}(Y)) \;. \end{split}$$

### Estimation with absolute error loss

- $\mathcal{M}(\rho(a)) = \sum w_i |a_i|$
- Regardless of the  $w_i$ 's, it is optimal to choose  $\delta(Y) = \check{\theta}$  such that  $P[\theta_i < \check{\theta}_i | Y] = .5$ , i.e.  $\check{\theta}$  is the element-wise median of  $\theta | Y$ .
- Notice that if  $\theta$  is  $\beta$  in the SNLM with a conjugate prior,  $\hat{\theta} = \check{\theta}$  and both are OLS applied to the data augmented by dummy observations.

## Non-Bayesian approaches to estimation

- Consider candidate δ(Y)'s, check the properties of the distribution of δ(Y) | θ. There are a variety of properties for this distribution that are considered desirable.
- $\delta(Y)$  is an **unbiased** estimator for  $\theta$  if and only if  $E[\delta(Y) | \theta] = \theta$  for every  $\theta$ .
- While this sounds kind of reasonable, it is important to note that it is quite different from the criterion for an optimal estimator under quadratic loss, which is instead  $E[\theta | Y] = \delta(Y)]$ . Indeed, if  $E[\delta(Y)^2] < \infty$ , it is impossible that an unbiased estimator coincides with  $E[\theta | Y]$ .

• Proof:  $E[(\delta(Y) - \theta)\theta] = 0$ , by definition of conditional expectation and  $E[\delta(Y) | \theta] = \theta$ . But

$$E[(\delta(Y) - \theta)\theta] = E[-(\delta(Y) - \theta)^2] + E[(\delta(Y) - \theta)\delta(Y)]$$
  
=  $-\operatorname{Var}(\delta(Y) - \theta) < 0, \rightarrow \leftarrow,$ 

unless of course  $\theta \equiv \delta(Y)$  so there is no estimation error at all.

• Note that this result does depend on there being a proper prior, so that the unconditional expectation of  $\theta$  is defined.