VAR System Properties from the Jordan Decomposition; cointegration

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The model

Suppose

\[ x(t) = \sum_{t=1}^{k} B(s)x(t-s) + \varepsilon(t), \]  

(1)

where \( \varepsilon(t) \) is the innovation in the \( x(t) \) vector. We can always rewrite (1) as a first-order system in a longer data vector \( y \) as
follows:

\[ y(t) = \begin{bmatrix} x(t) \\ x(t-1) \\ \vdots \\ x(t-k+1) \end{bmatrix} \]  \hspace{1cm} (2)

\[ y(t) = \begin{bmatrix} B(1) & B(2) & \cdots & B(k) \\ I_{(k-1)\cdot n} & & & 0 \end{bmatrix} y(t-1) + \begin{bmatrix} \epsilon(t) \\ 0 \end{bmatrix} \]  \hspace{1cm} (3)

We define \( \Gamma \) and \( \eta(t) \) by rewriting (3) as

\[ y(t) = \Gamma y(t-1) + \eta(t) \]  \hspace{1cm} (4)
Applying the Jordan decomposition

The Jordan decomposition of $\Gamma$ is

$$\Gamma = P\Lambda P^{-1}$$  \hspace{1cm} (5)

where $\Lambda$ is diagonal except that there may be along its diagonal “Jordan blocks” of the form

\[
\begin{bmatrix}
\lambda & 1 & 0 & \ldots & \ldots & 0 \\
0 & \lambda & 1 & 0 & \ldots & 0 \\
\vdots & \ddots & \ddots & \ddots & \ddots & \ddots \\
0 & \ldots & 0 & \lambda & 1 & 0 \\
0 & \ldots & \ldots & 0 & \lambda & 1 \\
0 & \ldots & \ldots & \ldots & \ldots & 0 & \lambda \\
\end{bmatrix}, \hspace{1cm} (6)
\]
i.e. constant down the main diagonal and equal to one on the
first diagonal above the main diagonal. (More concisely, \( \Lambda \) is
block diagonal with all the diagonal blocks Jordan blocks, though
some or all may be trivial \( 1 \times 1 \) Jordan blocks.) Any column of \( P \)
corresponding to the first row of a Jordan block (or to a \( 1 \times 1 \) Jordan
block) is a right eigenvector of \( \Gamma \). Corresponding rows of \( P^{-1} \) are
left eigenvectors.

If we define \( z(t) = P^{-1}y(t) \), then (5) implies

\[
z(t) = \Lambda z(t - 1) + \eta(t)
\]  

(7)

Every subvector \( z_i \) of \( z \) corresponding to a single Jordan block of \( \Gamma \)
constitutes a separate subsystem of (7),

\[
z_i(t) = \Lambda_i z_i(t - 1) + \eta_i(t).
\]  

(8)
In each of these subsystems, we can solve by recursive substitution to obtain
\[ z_i(t) = \Lambda_i^t z_i(0) + \sum_{s=0}^{t-1} \Lambda_i^s \eta_i(t - 1). \] (9)

For a Jordan block \( \Lambda_i \) with \( \lambda_i \) on the diagonal, \( \Lambda_i^p \) is an upper triangular matrix with \( \lambda_i^p \) on the main diagonal, \( p\lambda_i^{p-1} \) on the first diagonal above the main, \( p \cdot (p - 1) \lambda_i^{p-2} / 2 \) on the next diagonal, etc. The general formula is that the \( q \)'th diagonal above the main contains
\[ \lambda_i^{p-q} \binom{p}{q} \]
for \( q \leq p \), 0 for \( q > p \).\(^1\) Clearly if \( |\lambda_i| < 1 \), \( \Lambda_i^p \to 0 \) as \( t \to \infty \). In this case, if \( \eta_i \) satisfies \( E[\eta_i(t + 1) | x(t - s), \text{ all } s \geq 0] = 0 \) for all \( t \) and \( \eta_i \) has constant, finite variance, we can let the date of the initial

\(^1\)The notation \( \binom{p}{q} \) stands for the binomial coefficient \( p!/(q!(p-q)!). \)
condition in (9) recede into the past and obtain the limiting result

\[ z_i(t) = \sum_{s=0}^{\infty} \Lambda^s_i \eta_i(t - 1). \]  

(10)

Of course for this result to hold, the model equations must be thought of as having been in force for indefinitely long into the past.

If all the \( \eta_i \)'s are i.i.d. (for example — weaker assumptions would suffice), then \( z_i(t) \) clearly has the same distribution for all \( t \). This kind of \( z_i \) is called stationary or stable. If instead \( |\lambda_i| = 1 \), then the diagonal elements of \( \Lambda^p_i \) remain at one in absolute value for all \( p \), and the above-diagonal elements grow at a polynomial rate. If \( |\lambda_i| > 1 \), then all the elements of the upper triangle of \( \Lambda^p_i \) explode at least as fast as \( \lambda_i^p \) in absolute value.

If any \( \lambda_i \) is complex, then (assuming \( \Gamma \) is itself real), \( \lambda_i^* \), the
complex conjugate of \( \lambda_i \), also appears on the diagonal of \( \Lambda \), exactly as \( m \) times as \( \lambda_i \) itself appears, and the corresponding columns of \( P \) and rows of \( P^{-1} \) are conjugates of each other. Complex roots \( \lambda_i \) generate oscillatory behavior in the corresponding \( z_i(t) \).

But now from the definition of \( z \) we know that \( y = Pz \), so we know that \( y \) is a linear combination of elements of \( z \). Thus we can conclude that

i. If all the \( \lambda_i \) are less than one in absolute value, \( y \) itself, and hence \( x \), is stationary (being a sum of stationary \( z_i \)’s).

ii. If at least one of the \( \lambda_i \)’s is equal to one in absolute value, and none exceed one in absolute value, the initial condition term in 9, \( \Lambda^t z(0) \), contains components that eventually grow in absolute value at the polynomial rate \( t^m \), where \( m \) is the order of the
largest Jordan block $\Lambda_i$ matrix corresponding to one of the unit-
absolute-value $\lambda_i$’s.

iii. If any of the $|\lambda_i|$’s exceeds one in absolute value, $y(t)$ contains
components that explode exponentially as $t \rightarrow \infty$.

Often it is useful in interpreting a model to examine the
eigenvectors (columns of $P$ and rows of $P^{-1}$) corresponding to
various types of roots. For example, in data including several
nominal variables (prices, wages, money stock, current-dollar GDP,
etc.) in a country with high and variable inflation, we might
expect one unstable root to correspond to the aggregate price
level, contributing a non-stationary component to all the nominal
variables. The ratios of nominal variables to each other, on the
other hand, might be expected to be stationary. This implies that
we should find one $|z_i| \geq 1$ and that the corresponding row of $P^{-1}$ should put positive weight on a set of nominal variables. Also, if the variables are all measured in logs, the corresponding column of $P$ should have the same number in every row corresponding to a nominal variable in $y$. This would imply that nominal variables all move proportionately in response to the unstable component.
Cointegration

If the largest roots in absolute value are \( q \) in number and all equal to one another, and all of them correspond to trivial \((1 \times 1)\) Jordan blocks, then \( q \leq n \). Furthermore, in this case there are exactly \( n - q \) stationary linear combinations of \( x \) (not \( y \)). This is the situation known in the literature as **cointegration**. It is handy to know about, but the regularity condition required to deliver it — equality and non-repetition for the largest roots — is much more restrictive than reading the econometric theory literature might lead one to believe. These regularity conditions are widely and casually imposed without asking whether they have any foundation in economic reasoning. Nonetheless we proceed to discuss this case in detail and develop standard results.
We are always free to re-order the columns of $P$, the rows of $P^{-1}$, and the blocks on the diagonal of $\Lambda$, so long as all three are re-ordered in the same way. Thus we can always choose to have the diagonal elements of $\Lambda$ sorted in order of decreasing absolute value, and we now assume that this has been done. If just $q$ diagonal elements of $\Lambda$ are greater than 1 in absolute value, then the first $q$ elements of $z$ are non-stationary, while the last $nk - q$ are stationary. This result is much like the standard co-integration result, but it is not the same thing (and indeed may be more useful). The standard co-integration result, which we derive below, gives conditions under which there are $q$ non-stationary and $n - q$ stationary linear combination of $x(t)$, when there are $q$ elements of absolute value equal to 1 on the diagonal of $\Lambda$. The result we have arrived at here shows instead that, under weaker conditions, there are $q$ non-stationary and $nk - q$ stationary linear
combinations of $y(t)$ (since the $z(t)$’s are linear combinations of the $y(t)$’s). Notice that since $y(t)$ consists of current and lagged $x$’s, the stationary $z$’s may involve current and lagged $x$’s, not just current $x$’s.

It is immediately clear that, if there are exactly $q < n$ diagonal elements of $\Lambda$ that equal or exceed a value $\bar{\lambda}$ in absolute value, then there are at least $n - q$ linear combinations of $x(t)$ that grow more slowly than $\bar{\lambda}$. This follows because each element of $y(t)$, and hence each element of $x(t)$, is a linear combination of elements of $z(t)$. Since there are only $q$ elements of $z(t)$ that correspond to roots (diagonal elements of $\Lambda$) that equal or exceed $\bar{\lambda}$, it must be possible to find $n - q$ linear combinations of $x(t)$ that include no component of these $q$ overly explosive $z$’s. It may be possible to find more stationary linear combinations than
this, because it is not necessarily true that all $q$ non-stationary $z$’s receive weight in the linear combinations of $z$’s that form $x(t)$. It is a corollary of the argument given below that if there are any roots that equal or exceed $\bar{\lambda}$ in absolute value, there are no more than $n - 1$ linear combinations of $x(t)$ that grow more slowly than $\bar{\lambda}$.

Suppose that it were possible to form an “LU” decomposition of $P$, i.e. a decomposition of the form $P = VU$, with $V$ lower triangular with ones on the diagonal and $U$ upper triangular. In that case we could write

$$y(t) = Pz(t) = VUz(t), \quad \therefore \quad V^{-1}y(t) = Uz(t). \quad (11)$$

Because of the triangularity of $V$ and $U$, this expression implies that only the first $q$ elements of $y(t)$ (and hence the first $q$ elements of $x(t)$, assuming $q < n$) put any weight on the first $q$ elements of $z(t)$,
which are the \( q \) “excessively explosive” components of the system. All the remaining elements of \( V^{-1}y(t) \), and hence in particular the \( q + 1 \)’st through \( n \)’th, are stationary. But from the lower triangularity of \( V \) (which is preserved under inversion), we know that these \( n - q \) linear combinations of \( y(t) \) are actually just linear combinations of \( x(t) \). This brings us to the conclusion that there are exactly \( n - q \) linear combinations of \( x(t) \) that explode more slowly than \( \bar{\lambda} \).

This is not a proof that there are generally \( n - q \) non-explosive linear combinations of \( x(t) \), however, because even for a non-singular \( P \), it is not always possible to calculate an LU decomposition without what as known as “pivoting”. The condition that allows an LU decomposition without pivoting is that all the \( j \times j \) matrices formed from the upper left submatrix of \( P, j = 1, \ldots, nk \), be non-singular.\(^2\) What is always possible is to find permutation

\(^2\)See the description of the LU decomposition in Golub and van Loan, *Matrix Computations*
matrices\(^3\) \(Q\) and \(M\) such that \(QPM\) has an LU decomposition. To obtain the result that there are exactly \(n - q\) stationary linear combinations, we need to assure ourselves that, having ordered \(P\) and \(\Lambda\) so that the unstable roots are in the upper left, we can choose \(Q\) lower block triangular so that its first \(n\) rows are zero except in the first \(n\) columns, and choose \(M\) upper block triangular so that its last \(nk - q\) rows are zero in their first \(q\) columns.\(^4\) This means the first \(n\) elements of \(Qy(t)\) are still linear combinations of \(x(t)\) alone, and the last \(nk - q\) elements of \(M^{-1}z(t)\) are linear combinations of the last \(nk - q\) elements of \(z(t)\) alone. (This latter depends on the fact that \(M\)'s assumed block triangularity is preserved under inversion.)

\(^3\)A permutation matrix \(Q\) has all its elements 0 or 1 and satisfies \(Q'Q = I\). Multiplication of a matrix by a permutation matrix simply reorders its rows or columns.

\(^4\)Note that a block triangular permutation matrix must be block diagonal.
A sufficient condition for our being able to choose $Q$ and $M$ this way is that the upper left $n \times q$ submatrix of $P$ be of full column rank $q$, since in that case we can use row pivoting on the first $n$ rows of $P$ (i.e. choose

$$Q = \begin{bmatrix} Q_{11} & 0 \\ n \times n \\ 0 & I \end{bmatrix}$$  \hspace{1cm} (12)$$

to make the upper left $q \times q$ matrix of $QP$ non-singular, then use column pivoting on the last $nk - q$ columns (i.e. choose

$$M = \begin{bmatrix} I & 0 \\ nk - q \times nk - q \\ 0 & M_{22} \end{bmatrix}$$  \hspace{1cm} (13)$$

to complete the LU decomposition. A sufficient condition for the upper left $n \times q$ submatrix of $P$ to be of rank $q$ is that $\Lambda_{11}$, the
upper left $q \times q$ submatrix of $\Lambda$, is of the form $\lambda I$. This implies that all non-stationary roots are of the same size and have unit multiplicity (i.e. correspond to $1 \times 1$ Jordan blocks.) The most common assumption is that all these roots are unit roots, i.e. $\lambda = 1$. Under this assumption we know that the upper left $n \times q$ sub-matrix of $P$ is of full column rank. To see this, note that the first $q$ columns of $P$, a $kn \times q$ matrix we label $c$, is under these conditions a set of right eigenvectors of $\Gamma$ corresponding to the eigenvalue $\lambda$ and thus, using the definition of $\Gamma$ in terms of $B(L)$, satisfies

$$c_i = c_{i+1} \lambda, \quad i = 1, \ldots, k - 1,$$

where $c$ has been broken up into the $k n \times q$ blocks $c_1, \ldots, c_k$. Thus if $c_1$ is of less than full column rank, there is a $q \times 1$ vector $\gamma$ such that not only $c_1 \gamma$, but by (14) $c_i \gamma$ for every $i$, is zero. This would imply that $c$ itself is less than full column rank, which is by
construction not true. Thus $c_1$ must be of full column rank $q$. Since $c_1$ is $n \times q$, this lets us conclude that $q \leq n$, certainly. Also, as we have already observed, that $c_1$ is of rank $q$ implies that there are exactly $n - q$ linearly independent stationary linear combinations of elements of the current $x$ vector. Summarizing our results, we arrive at

**Proposition 1.** *If the $q$ largest eigenvalues of $\Gamma$ in (3) are all equal and non-repeating, then $q \leq n$ and there are $n - q$ stationary linear combinations of $x(t)$.***

The coefficients of these linear combinations are what is known as **cointegrating vectors**.

Now we can give a description of a fairly straightforward algorithm for locating cointegrating vectors:
i. Find the $q$ left eigenvectors of $\Gamma$ corresponding to the $q$ equal, maximal roots.

ii. If necessary, re-order the variables in $x$ so that the upper left $j \times j$ submatrix of the $q \times nk$ matrix formed by these eigenvectors is non-singular, all $j \leq q$.

iii. Find $n - q$ additional left eigenvectors of $\Gamma$ (corresponding to other roots) such that when these are placed below the first $q$ to form the $n \times nk$ matrix $P^1$, the upper left $j \times j$ submatrix is nonsingular, $j = q + 1, \ldots, n$.

iv. Perform an LU decomposition of the resulting corresponding re-ordered $P_{11}$, the upper left $n \times n$ submatrix of $P$, so that $P_{11} = UV$ and $P^{11} = V^{-1}U^{-1}$, with $V$ lower triangular and $U$ upper triangular.
Then the \( q + 1 \)st through \( n \)th rows of \( V^{-1} \) contain the cointegrating vectors.
Examples

The simplest example of a system with $q$ unit roots and more than $n - q$ stationary linear combinations is

\begin{align}
(1 - L)^2 y_1(t) &= \varepsilon_1(t) \quad (15) \\
y_2(t) &= \varepsilon_2(t) \quad (16)
\end{align}

There are two (repeating) unit roots in this $2 \times 2$ system, and nonetheless 1 stationary linear combination, $y_2$. Other simple examples can be constructed by taking linear transformations of
this one, say

\[ z_1(t) = 4z_1(t - 1) - 4z_2(t - 1) - 2z_1(t - 2) + 2z_2(t - 1) + \eta_1(t) \]  
(17)

\[ z_2(t) = 2z_1(t - 1) - 2z_2(t - 1) - z_1(t - 2) + z_2(t - 2) + \eta_2(t) . \]  
(18)

This system is obtained by letting \( z(t) = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} y(t), \) and it therefore also has two repeating unit roots and one stationary linear combination, which is here \( 2z_2(t) - z_1(t). \)