

### EXERCISE ON WOLD DECOMPOSITION, ARMA MODELS

- (1) In all of the models below,  $\varepsilon_t$  is i.i.d.  $N(0, 1)$  and  $y_t$  is a stationary process. Though they have different coefficients, not all of them define different distributions for  $y_t$ . Which pairs define identical stochastic processes?

$$y_t = .7y_{t-1} + \varepsilon_t - .9\varepsilon_{t-1} \quad (1.1)$$

$$y_t = 2.9y_{t-1} - 2.8y_{t-2} + .9y_{t-3} + \varepsilon_t - 2\varepsilon_{t-1} + \varepsilon_{t-2} \quad (1.2)$$

$$y_t = .9y_{t-1} + \varepsilon_t - .7\varepsilon_{t-1} \quad (1.3)$$

$$y_t = 1.7y_{t-1} - .95y_{t-2} + .175y_{t-3} + \varepsilon_t - 1.9\varepsilon_{t-1} + 1.15\varepsilon_{t-2} - .225\varepsilon_{t-3} \quad (1.4)$$

$$y_t = .9y_{t-1} + \varepsilon_t \quad (1.5)$$

- (2) The stochastic process  $y$  is a finite-order moving average of the form

$$y_t = \varepsilon_t + 1.7\varepsilon_{t-1} + .7\varepsilon_{t-1}$$

with  $\varepsilon_t$  i.i.d.  $N(0, 1)$ .

- (a) Show that this process does not have an AR representation, even if we allow infinitely many lags.
- (b) Determine the form of the best predictors of  $y_t$  based on 2, 5, and 10 lagged values of  $y$  and compare the forecast error variance of these approximations to the forecast error variance of  $E[y_t | \{y_s, s = -\infty, \dots, t-1\}]$ . [You'll need to use a computer. The `toeplitz` functions in R and Matlab should be helpful.]
- (3) Again all the models below have i.i.d.  $N(0, I)$   $\varepsilon$  processes, and in each,  $y$  is stationary. For each model, find the fundamental MAR and compare the variance of the innovation to the variance of  $\varepsilon$ .

$$y_t = \varepsilon_t + 2\varepsilon_{t-1} + 1.1\varepsilon_{t-2} \quad (3.1)$$

$$y_t = \varepsilon_t - 2\varepsilon_{t-1} + .99\varepsilon_{t-2} \quad (3.2)$$

$$y_t = \varepsilon_t + \begin{bmatrix} 0 & 5 \\ 0 & 0 \end{bmatrix} \varepsilon_{t-1}. \quad (3.3)$$

In the first two of these,  $y$  is scalar, while in the last, both  $y$  and  $\varepsilon$  are two-dimensional.

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